

Is there only one type of ecosystem? Axioms for community ecology

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“... the climax constitutes the major unit of vegetation and as such forms the basis for the natural classification of plant communities.”

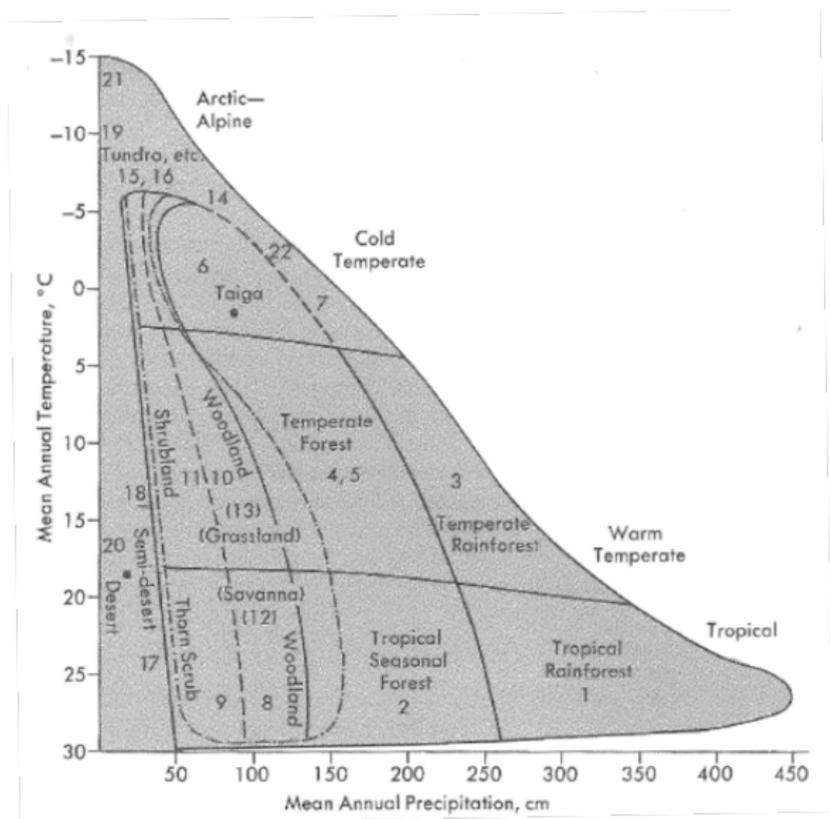
Henry Allan Gleason



“... the tendency of the human species is to crystallize and to classify his knowledge; to arrange it in pigeon-holes ...”

Sources: Photo NYBG Staff Photographer - The Vertical Files of the LuEsther T. Mertz Library of the New York Botanical Garden, CC BY-SA 4.0, <https://commons.wikimedia.org/w/index.php?curid=73086860>; quotation Gleason 1926 Bull. Torrey Bot. Club 53:7.

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- We really want types of ecosystem that are divided “where the natural joints are.”³
- Finding non-arbitrary divisions into types is not always easy, e.g. x is a human \iff x is a featherless biped?

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Two humans



Image: David Clifford/The Guardian, <https://www.theguardian.com/lifeandstyle/2022/oct/22/the-dog-that-walks-like-a-human-and-other-precocious-pets-duck-cat-parrot>

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- A set of five *apparently* self-evident statements about geometry⁴.

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- Example: the *parallel axiom* P_1 : “for each straight line L and point P outside L , there is exactly one line through P that does not meet L ”⁵

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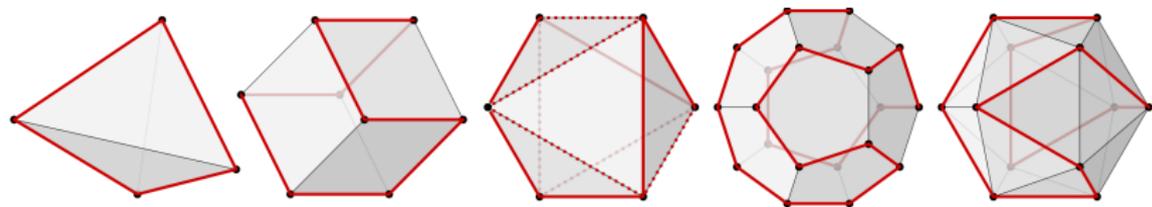
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- Example: the *parallel axiom* P_1 : “for each straight line L and point P outside L , there is exactly one line through P that does not meet L ”⁵
- We can get a lot of results from these axioms and not much else, e.g. that there are only 5 convex regular polyhedra in \mathbb{R}^3 .

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The Platonic solids



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- Replace the parallel axiom by P_2 : there are at least two lines through a point P that do not meet line L^6 .
- We get a different but internally consistent geometry called *hyperbolic geometry*, which we can think of as geometry on surfaces with negative curvature.

⁶Stillwell, p 361

Hyerbolic geometry



Image by Margaret Wertheim - originally posted to Flickr as crochet hyperbolic kelp, CC BY 2.0,
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- These axioms alone are not strong enough to give us many results.

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Andrej Kolmogorov



Photo by Konrad Jacobs - <https://opc.mfo.de/detail?photoID=7493>, CC BY-SA 2.0 de,
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- These axioms (plus real analysis) allow only three possible behaviours: approach equilibrium without oscillations or with damped oscillations, or sustained oscillations.

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Recent axiomatic approaches in ecology

- Theory-based ecology¹⁰: Hutchinson plus inherited individual differences, demographic stochasticity, genetic constraints.
- Clone-consistent ecosystem models¹¹: arbitrarily splitting or aggregating populations with the same properties should not change the outcome.

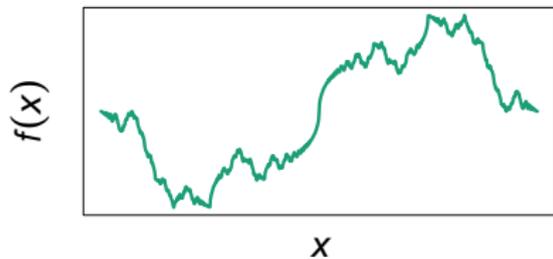
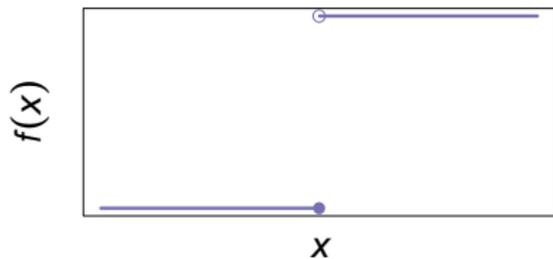
¹⁰Pásztor et al. 2016

¹¹Ansmann and Bollenbach 2021 PLoS Computational Biology 17:e1008635

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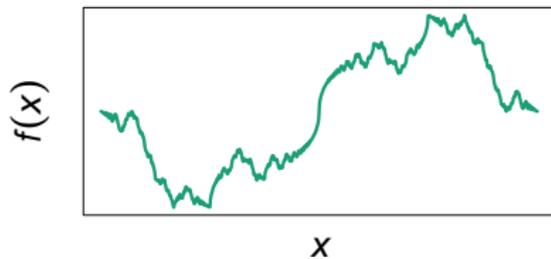
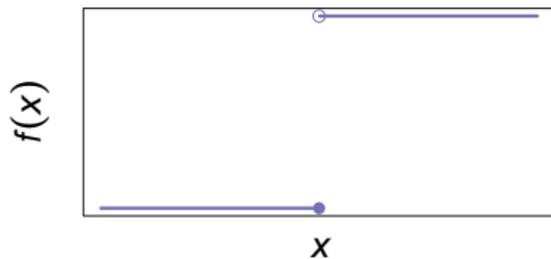
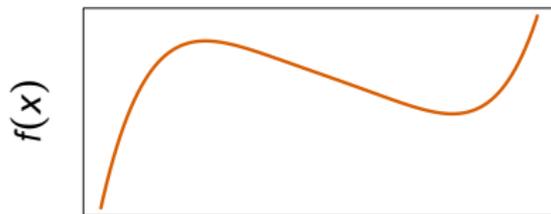
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Properties of functions



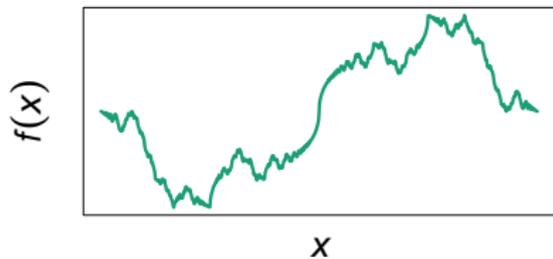
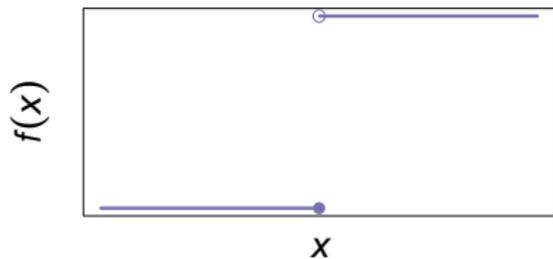
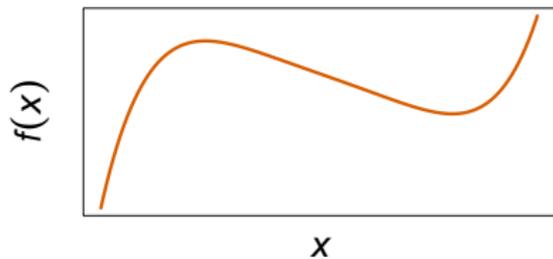
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- Continuous functions can still be “badly-behaved” in some ways, e.g. nowhere differentiable.

The image of a connected space under a continuous function is connected

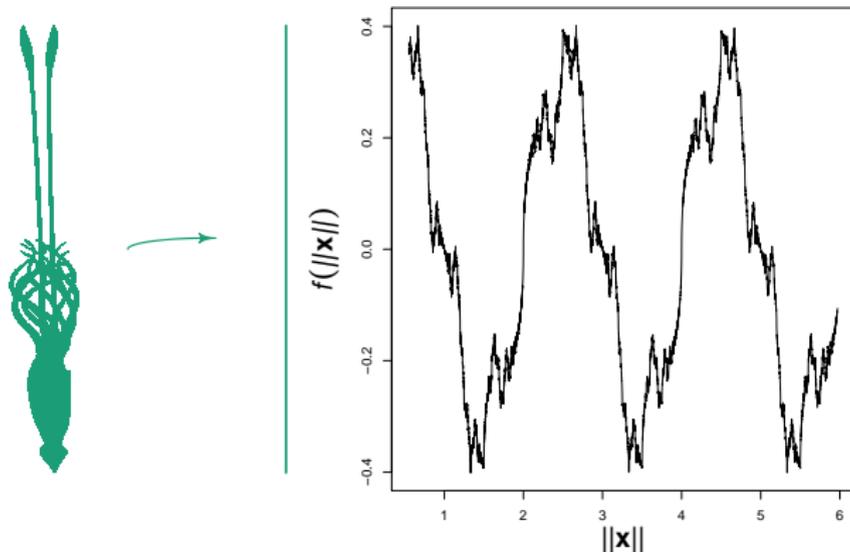


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- Let C be an $|S| \times |S|$ matrix such that $c_{nm} \in C^\infty(\mathbb{R}_+)$: how is consumed m converted into biomass of n ?

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 - 7 (Inefficient Conversion): we get less predator biomass than prey biomass consumed.

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 - 4 Scalar multiplication of interaction effects (everything happening faster or slower).
- These are generative axioms: there are corresponding limitative axioms that generate the same set of ecosystems top-down.

If $e = (S, G, P, C)$ is a G -ecosystem, then abundance $x_{s_n}(t)$ of species s_n at time t is a solution of the Kolmogorov equation

$$\begin{aligned} \frac{dx_{s_n}}{dt} = & x_{s_n} \left(g_{s_n, s_n}(x_{s_n}, x_{s_n}) \right. \\ & + \sum_{s_m: P(s_n, s_m)=1} c_{s_n, s_m} (g_{s_n, s_m}(x_{s_n}, x_{s_m}) x_{s_m}) \\ & \left. + \sum_{s_j: P(s_j, s_n)=1} g_{s_j, s_n}(x_{s_n}, x_{s_j}) \right) \end{aligned}$$

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- Hence under these axioms, there is only one type of ecosystem.

Sensible measurements on ecosystems are continuous functions

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$$\text{size} = \begin{cases} \text{"small"}, & \text{if total biomass} < 100, \\ \text{"large"}, & \text{otherwise.} \end{cases}$$

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- If we really believe that there is more than one interesting type of ecosystem, what other axioms do we need?



Dynamic assignment function

We say that ψ is a dynamic assignment function if and only if for all $n, m \in \mathbb{N}$:

- 1 (Prey Consumption and Predator Growth) if $P(n, m) = 1$ then for all $x, y \in \mathbb{R}_+$, $g_{n,m}(x, y) > 0 > g_{m,n}(x, y)$
- 2 (Producers can Increase when Rare) if $P(m, n) = Prod$ then $n = m$ and there is a $b_n \in \mathbb{R}_+$ such that if $x < b_n$ then $g_{n,n}(x, x) > 0$
- 3 (Only Predation and Production) if $P(m, n) = 0$ and $n \neq m$ then $g_{m,n}(x, y) = 0$
- 4 (Non-producers need Prey) if $P(n, n) \neq Prod$ then $g_{n,n}(x, x) < 0$
- 5 (Producers are Self-Limiting) if $P(n, n) = Prod$ then $g_{n,n}(x, x)$ is strictly decreasing in x
- 6 (Monotonicity) if $P(n, m) = 1$ then $g_{n,m}(x, y)$ is strictly increasing in y and $g_{m,n}(x, y)$ is strictly decreasing in x .
- 7 (Inefficient Conversion) If $P(m, n) = 1$ then $0 \leq c_{m,n}(s) < s$, otherwise $c_{m,n} = 0$